



An Intelligent Color Image Recognition and Mobile Control System for Robotic Arm

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ABSTRACT

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The aim of this study is to develop intelligent color recognition, mobile control, and monitoring system for a pick-and-place robotic arm for manufacturing systems. The demand for smart manufacturing factories with real-time control of fabricating processes and traceability of production information is increasing urgently. Generally speaking, a smart manufacturing facility is usually composed of sensing, computing, control, and communication technologies together. In this study, the three-tier architecture of the Internet of things (IoT) was adopted as a guideline to design mobile devices to control and monitor a color image recognition and alarm monitoring system by using Raspberry Pi and a web page database. The practical results and contributions of this study are as follows: With integrating the techniques of advanced B&R PLC, mobile devices and APP, color image recognition, Raspberry Pi microcomputer, and MySQL database technologies together, (1) the mobile control and monitoring system is able to supervise a real-time manufacturing plant anywhere and anytime with mobile devices easily; (2) the color identification system can identify and classify different color work-piece precisely, and the identification results are recorded for remote database platform; (3) the collected data are analyzed and displayed on mobile devices through the web database for field operators and engineers promptly. It provides a very successful practical paradigm to promote conventional factories to meet industry 4.0.

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1. Introduction

Under the trend of industry 4.0, the manufacturing industry is facing the issue of transformation. A manufacturing facility is necessary to integrate physical equipment, sensors, and communication technology through the virtual and real system [1-6]. In order to achieve the cooperation of humans and machines, the factory is expected to drive the improvement of efficiency and flexibility of the manufacturing process. Because of the lack of workforces, the enterprise also urgently needs to promote traditional manufacturing plants to a smart manufacturing factory [7-18]. The traditional manufacturing plant needs to capture, monitor, and analyze the status and operation data of the facility in real-time to meet the demand of managing production and predictive maintenance [19-24].



Moreover, sensing, computing, control, and communication technologies are required to form up a smart production system [25-27]. The data of status and information of production facility are needed to collect and calculate statistically to provide prompt fabricating information to the operator and engineer/manage staff [28-30].

The following techniques are employed in this study: (1) image processing and identification technology of Raspberry Pi, (2) remote web database technology of MySQL, and (3) monitoring and alarm technology of the mobile device. Fig. 1 shows the proposed systematical diagram of this study based on the principle of the three-tier architecture of IoT. It well explains the related technologies and system construction of color image identification technology and remote database web technology, respectively. Fig. 2 depicts the hardware connection for the web database system.



Fig. 2. Hardware connection for Web Database System

2. Method

In this study, an advanced B&R PLC and Raspberry Pi microcomputer are employed to carry out the tasks of online real-time monitoring and alarm and color image identification. It provides more competitive and flexible functions for intelligent automatic control system applications. Fig. 3 shows the configuration layout of the system. Fig. 4 illustrates the robot arm for the manufacturing system.

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Among them, image processing and identification technology of Raspberry Pi mainly employ USB cam to capture images and store them in Raspberry Pi then converts the image RGB color format into HSV color format, and then carries out the binarization of OpenCV and shape processing for color recognition, and the remote web database technology of MySQL collects data through GPIO pinout of Raspberry Pi and records the data in the MySQL. Fig. 5 and Fig. 6 show the LINE notification Python code and Gmail Python code for sending messages, respectively. These programs are mainly used to trigger the GPIO pin of Raspberry Pi to record down the data when the device exception condition is reached, and then send out a prompt message to users.



Fig. 3. System configuration.



Fig. 4. Robot arm for the manufacturing process.



Fig. 5. Python code of LINE notification.

send_user = 'stu @gmail.com' Sender password = ' mail mail Addressee subject = timeNowAlarm + ' 没個異常認思想'' #MC Message body email text = '\n+' bear sir.'+' \n\n' + text Message body server address = 'smtr.gmail.com' Server address mail_type = '1' #MFEM Server address	#攝達郵件附件 #file = file #攝眼檔案路徑 part_attach1 = MIMEApplication(open(picURI,'rb').read()) #開啟附件 part_attach1.add header('Content-Disposition','attachment',filename=picURI) msg.attach(part_attach1) #新增附件
#環過一個聯件體:正文 附件 msg = MIMEMultipart() msg['Subject']=subject #主題 msg['To']=receive_user #設件人 msg['To']=receive_users #設件人 #標識正文 part_text=MIMEText(email_text) msg_attach(part text) #把正文加別部件書增置去	# 傳送部件 SMTP smtp= smtplib.SMTP_SSL('smtp.gmail.com', 465) smtp.login(send user, password) smtp.sendmail(send user, receive_users, msg.as_string()) print('簕件傳送成功!') smtp, quit()

Fig. 6. Python code of Gmail notification.

3. Results and Discussion

In the mobile monitoring and alarm function, the main screen displays the basic operational information of the process, such as the position of the robot arm, work piece in place, the status of sensors, start button, emergency stop button, and screen page change button. In Fig. 7, the real-time synchronous operation is displayed on both the on-site man-machine interface (HMI) screens and mobile devices simultaneously. In Fig. 8, the system will send alarm messages to the line app of the user group and email on mobile devices, respectively. The line group and the specific mailbox will receive the notification of the alarm messages at the same time the malfunction of the manufacturing process occurs.



Fig. 7. Real-time synchronous operation display on both HMI and mobile device.



Fig. 8. Real-time line app group fault message notification.

The USB camera is installed next to the robotic arm. It will recognize the image of different colors immediately when the arm lowers down toward the work piece, and the pick-and-place arm will clamp

the work piece to the correct position. The color image identification system shows the color ID of work piece to facilitate the camera for recognizing the color image. The identified work piece was labeled with three colors red, green, and blue. In Fig. 9, after the color recognition teaching procedure is performed first, then the work piece is randomly placed in the feeder, the result of color identification is sent to the HMI and flat panel display.



Fig. 9. The color identification system and its operation result are displayed on the HMI and flat-panel, respectively.

The acquisition of operational data is acquired to the database platform via the Python of Raspberry Pi computer. It provides real-time query of web platform after stacking. Fig. 10 and Fig. 11 show the data format and the display of real-time production information for web browser and MySQL database on the web pages, respectively.

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	2	0	0	1	0	0	2020-	04-13 18:47:03	3				- 1
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Fig. 10. MySQL database of recorded data.



Fig. 11. Remote web page of production status.

4. Conclusions

In this study, a color image identification and monitoring and alarm system for a pick-and-place robot arm of manufacturing system were developed successfully. It integrates the advanced PLC, Raspberry Pi microcomputer, and MySQL database technologies together. It includes the system integration of hardware and software programming of PLC&HMI, MySQL database, line app, and Gmail of mobile devices configuration. The mobile control and monitoring function can supervise the status and malfunction information of the factory via the user group line app and email concurrently. In addition, it also provides remote connection of HMI and mobile devices through the VNC software for remote control and monitoring the fabrication facility. The functions of color image recognition and remote web page database can identify the color ID of work piece with USB camera, and the operational results were recorded and sent to the remote MySQL-based data acquisition system, and then generate information charts on the web page screen which provides information of maintenance and operation to operators and engineers. The novelty of this proposed system is adopting open-shelve equipment and tools, such as the advanced B&R PLC, USB camera, Raspberry Pi microcomputer, and MySQL database technologies together. It can easily promote a conventional factory to an intelligent one to improve the efficiency and feasibility of the manufacturing facility for Industry 4.0. The future works are as follows: (1) The image recognition function can be added with the shape, size, or bar code of work pieces, so as to bring more image recognition and more diversities of production processes; (2) The acquired information of the manufacturing plant can use to analyze and generate more useful fabrication intelligence for later smart manufacturing application.

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